

A SHORT INTRODUCTION TO TWO-PHASE FLOWS

Void fraction:

Experimental techniques and simple models

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PHASE PRESENCE FUNCTION

- Phase presence function definition:

$$X_k(\mathbf{r}, t) \triangleq \begin{cases} 1 & \text{si } M(r) \in \text{phase } k, \\ 0 & \text{si } M(r) \notin \text{phase } k. \end{cases}$$

- Phase indicator, *FIP*, *fonction indicatrice de phase*, χ_k .
- Space averaging:

$$\text{Conditional, } \langle f \rangle_n \triangleq \frac{1}{D_{kn}} \int_{D_{kn}} f_k dV,$$

$$\text{Plain, } \langle f \rangle_n \triangleq \frac{1}{D_n} \int_{D_n} f dV.$$

AVERAGING OPERATORS (CT'D)

- Time averaging:

$$\text{Conditional, } \overline{f}_k^X(t) \triangleq \frac{1}{T_k} \int_{[T_k]} f(\tau) d\tau,$$

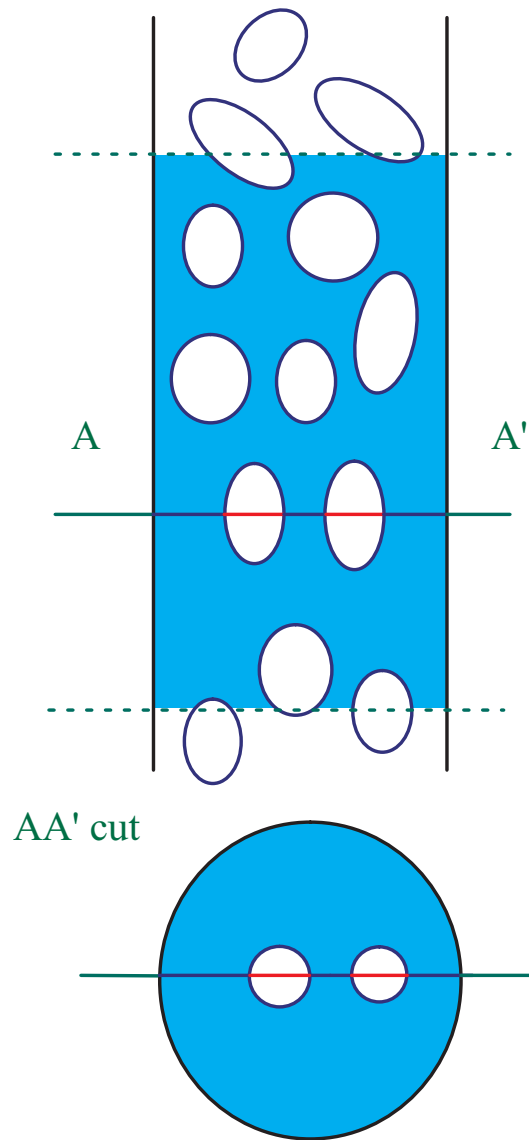
$$\text{Plain, } \overline{f}(t) \triangleq \frac{1}{T} \int_{[T]} f(\tau) d\tau.$$

- Commutativity of averaging operators:

$$\overline{R_{kn} < f_k >_n} = \nless \alpha_k \overline{f}_k^X \nless n.$$

- Void fraction: average of the phase presence function
- Void fraction, gas hold-up: *taux de présence du gaz, taux de vide.*

VOID FRACTION (α)



- Local time fraction (gas, void fraction) :

$$\alpha_G(\mathbf{r}, t) \triangleq \overline{X_G} = \frac{T_G}{T}.$$

- Instantaneous space fraction.

- Line fraction:

$$R_{G1}(t) \triangleq \langle X_G \rangle_1 = \frac{L_G}{L_G + L_L} = \frac{L_G}{L}$$

- Area fraction:

$$R_{G2}(t) \triangleq \langle X_G \rangle_2 = \frac{A_G}{A_G + A_L} = \frac{A_G}{A}$$

- Volume fraction:

$$R_{G3}(t) \triangleq \langle X_G \rangle_3 = \frac{V_G}{V_G + V_L} = \frac{V_G}{V}$$

BASIC IDENTITIES

- Commutativity ($f = 1$): $\overline{R_{kn}} = \overline{\langle \alpha_k \rangle_n} = \overline{\langle X_k \rangle_n}$.
- Mean phase fraction.

- Mean line-averaged,

$$\overline{R_{G1}} = \frac{1}{T} \int_{[T]} R_{G1}(\tau) d\tau = \frac{1}{L} \int_L \alpha_G dL$$

- Mean area-averaged,

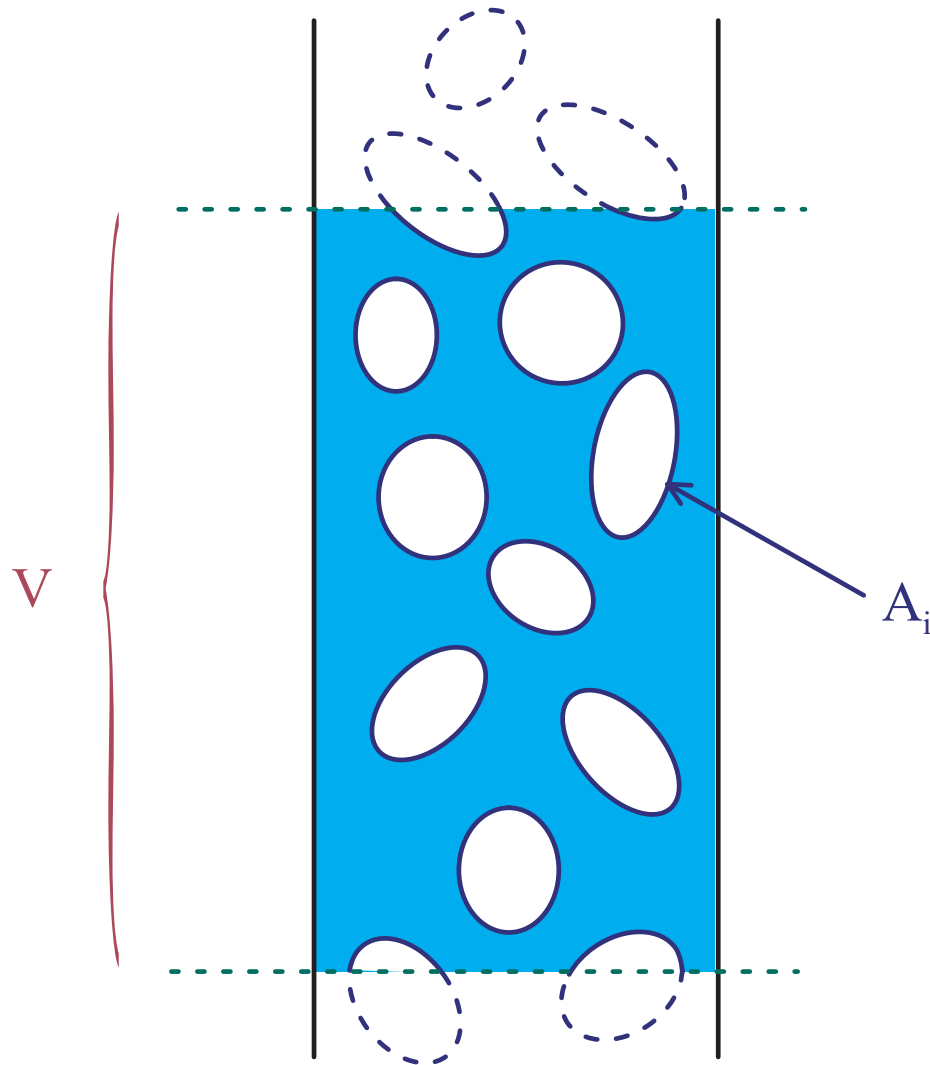
$$\overline{R_{G2}} = \frac{1}{T} \int_{[T]} R_{G2}(\tau) d\tau = \frac{1}{A} \int_A \alpha_G dA$$

- Mean volume averaged,

$$\overline{R_{G3}} = \frac{1}{T} \int_{[T]} R_{G3}(\tau) d\tau = \frac{1}{V} \int_V \alpha_G dV$$

- 7 precise definitions of the void fraction. The one to keep depends on the context (model). VF is always some average of X_k .

OTHER RELATED DEFINITIONS



- Instantaneous interfacial area:

$$\Gamma_3(t) \triangleq \frac{A_i(t)}{V}$$

- Local interfacial area, is a time-averaged quantity:

$$\gamma = \sum_{\text{disc.} \in [T]} \frac{1}{|\mathbf{v}_i \cdot \mathbf{n}_k|}$$

- Identity (commutativity of interaction terms), mean interfacial area:

$$\overline{\Gamma}_3 \equiv \langle \gamma \rangle_3$$

- Γ_3 and γ can be measured.

EXPERIMENTAL TECHNIQUES FOR VOID FRACTION

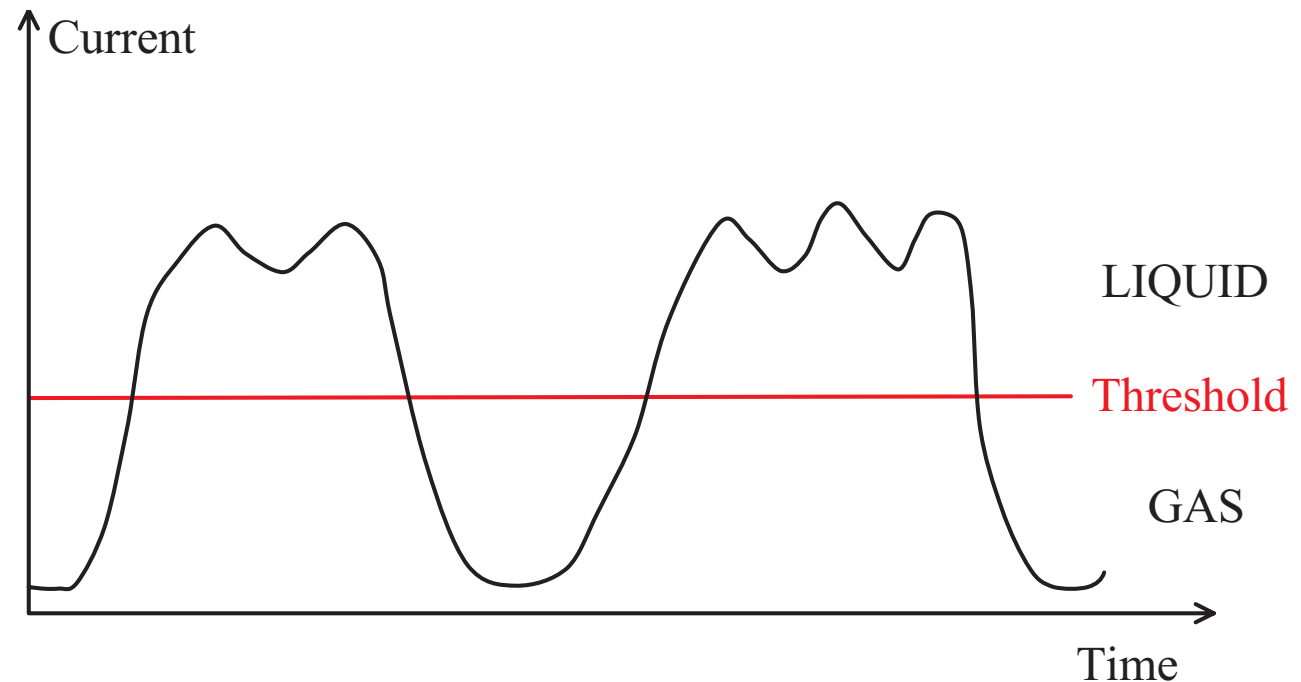
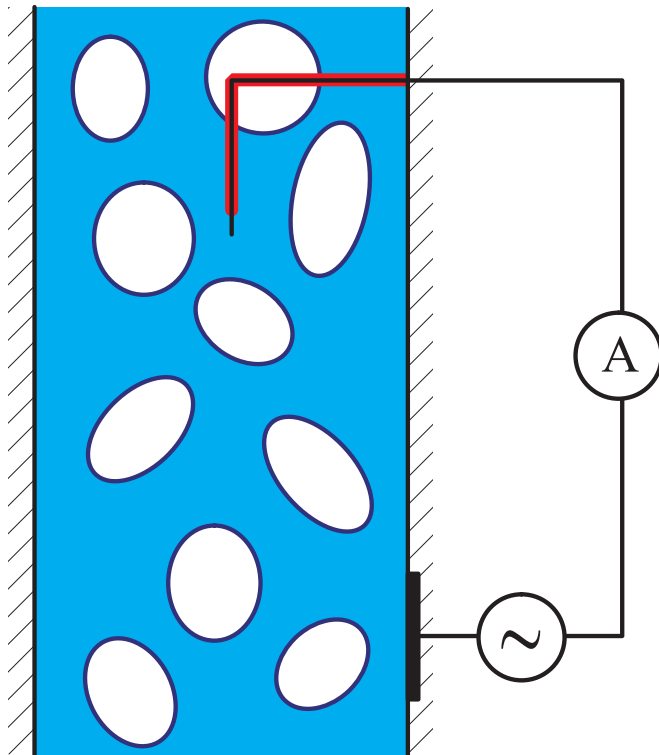
- Local void fraction.
 - Electrical probes
 - Optical probes
- Line averaged void fraction.
 - Light attenuation (X or γ rays)
- Area-averaged void fraction.
 - X-rays ou γ -rays, (one-shot)
 - Multi-beam densitometry
 - Neutrons diffusion (steel, steam-water, HP-HT)
 - Impedance probes
- Volume averaged void fraction,
 - Quick closing valves,
 - Gravitational (hydrostatic) pressure drop,
 - Ultrasound attenuation ([Bensler, 1990](#)).
- Medical imaging, CT, MRI.

LOCAL VOID FRACTION

Electrical probes (different resistivity):

Determination of the liquid phase indicator, $X_L(\mathbf{r}, t)$.

- Continuous phase (water), conducting,
- Dispersed phase (air), non conducting
- Threshold on current $\rightarrow X_L \rightarrow \alpha_L$

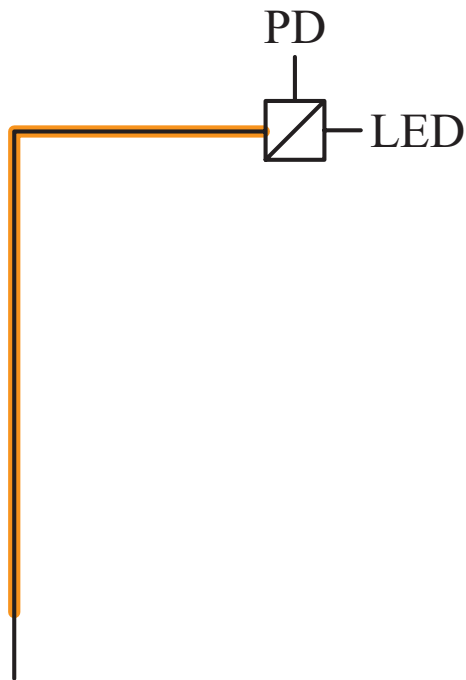


LOCAL VOID FRACTION

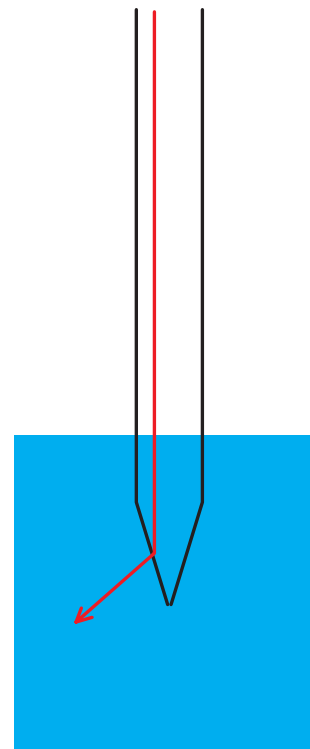
Optical probes (different refraction index) :

Determination of the gas indicator, $X_G(\mathbf{r}, t)$.

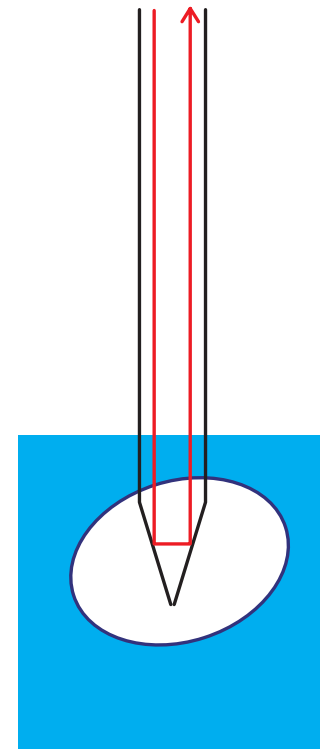
Principle: dish washer, rinsing liquid level indicator.



Water, freons, $T < 110^\circ\text{C}$

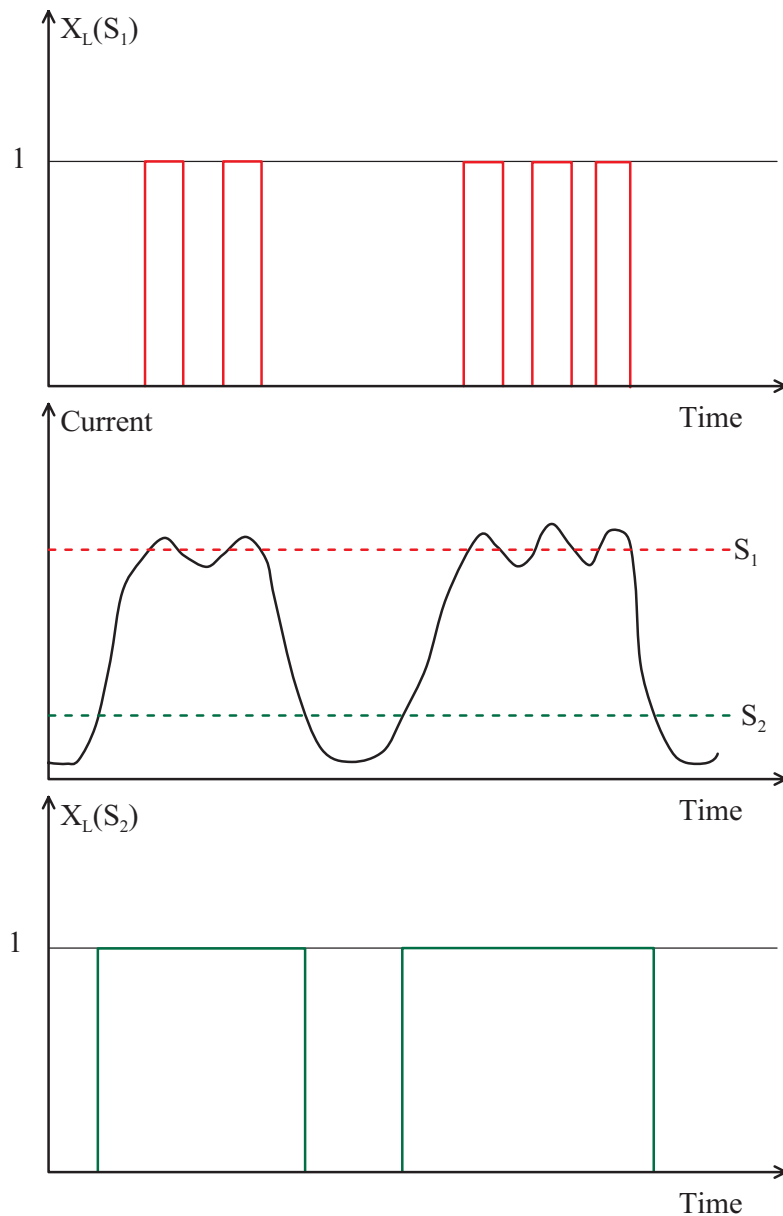


Water:
Refraction



Air:
Reflexion

HOW TO SET THE THRESHOLD LEVEL?



- $\alpha = \overline{X_L}$, depends on threshold:

$$S_1 > S_2 \Rightarrow \alpha_{L1} < \alpha_{L2}.$$

- Reference method:

$$\Delta p \rightarrow \overline{R_{G2}}$$

- It is recalled,

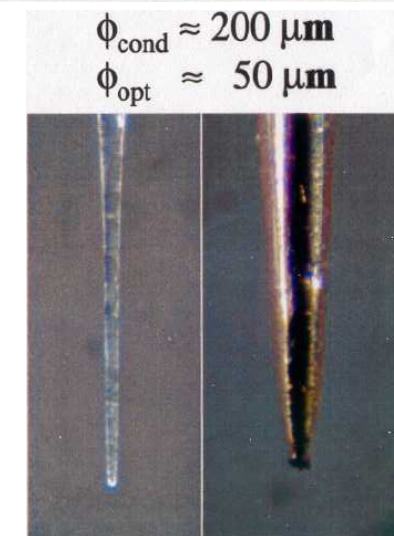
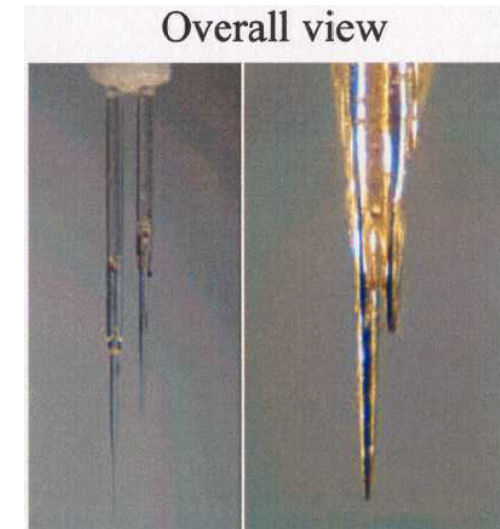
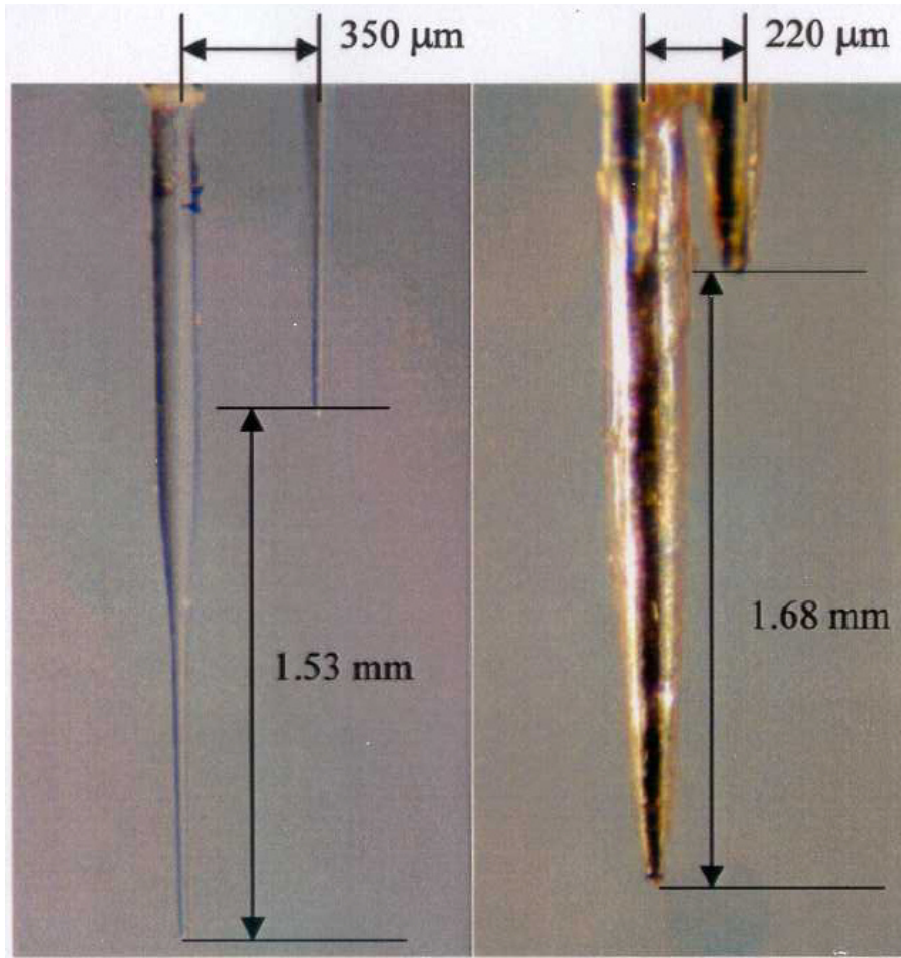
$$\langle \alpha_G \rangle_2 = \overline{R_{G2}}$$

- Determine $\alpha_G(S)$ on the section.
Find S such that,

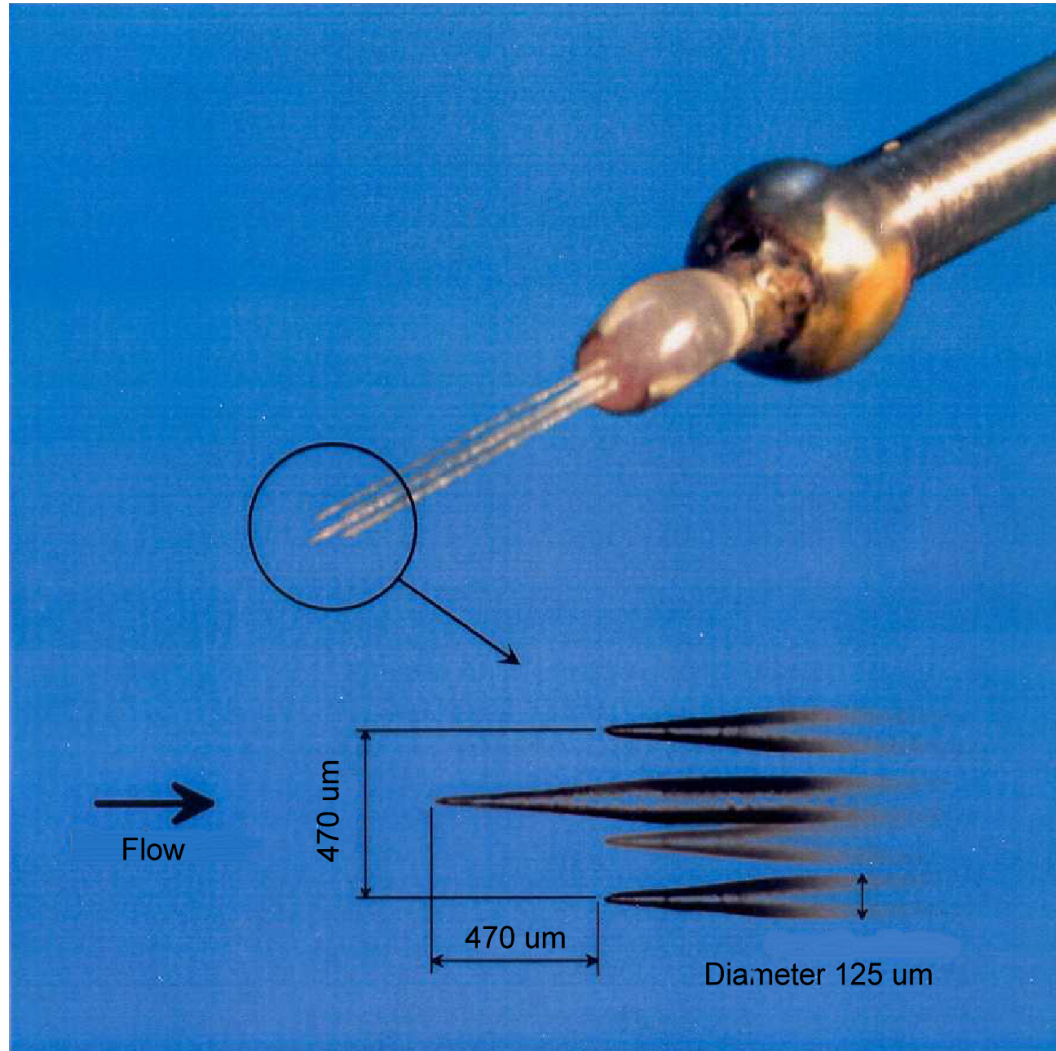
$$\langle \alpha_G(S) \rangle_2 = \overline{R_{G2}}$$

- Consistency check, not a calibration.

ELECTRICAL & OPTICAL PROBES



MULTIPLE TIP SENSORS



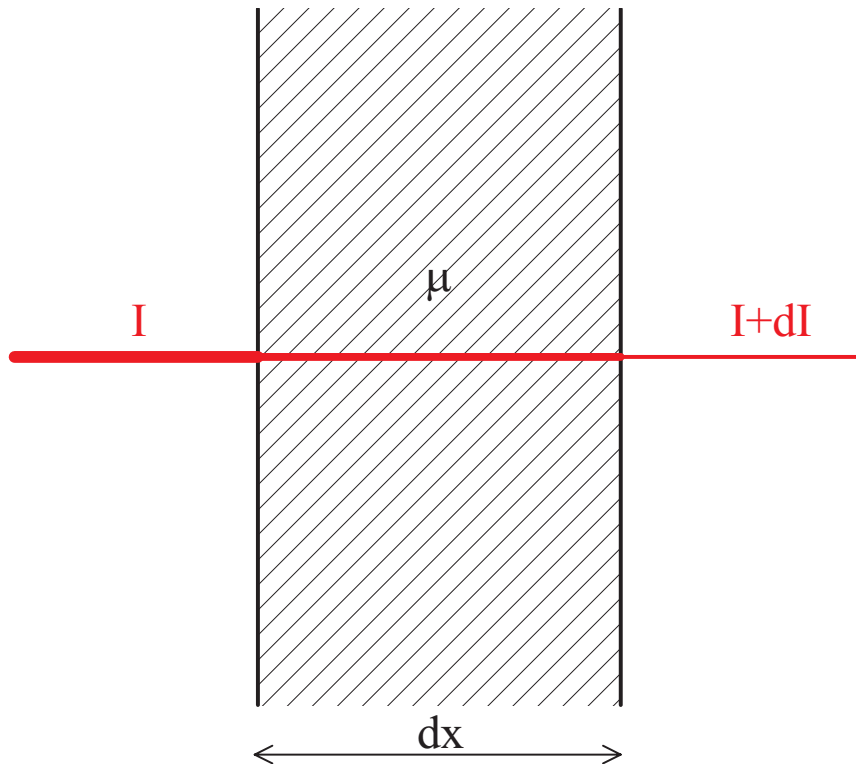
- 2-sensor probe. Add assumptions: spherical bubbles, chord distribution → mean diameter, mean gas velocity.
- 4-sensor probe. Determine interface orientation ($\mathbf{n}_k$), geometrical surface velocity, $\mathbf{v}_i \cdot \mathbf{n}_k$
- Local interfacial area,

$$\gamma = \sum_{\text{disc.} \in [T]} \frac{1}{|\mathbf{v}_i \cdot \mathbf{n}_k|}$$

- Mean sauter diameter (D_{32}), identity (bubbles),

$$\gamma \equiv \frac{6\alpha}{D_{SM}}$$

LIGHT (PHOTONS) ATTENUATION

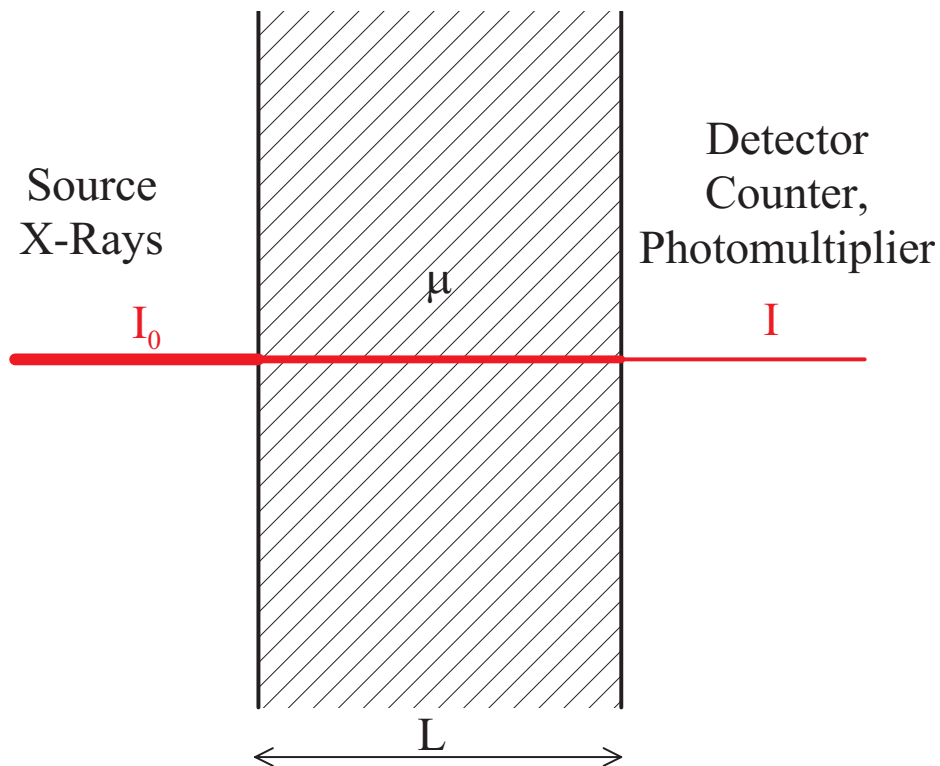


- X-rays or γ -rays.
- Collimated beam, single spectral line
- Beer-Lambert relation:

$$dI = -\mu I dx, \quad [\mu] = \text{L}^{-1}$$

- Exponential absorption, μ absorption coefficient.
- $\frac{\mu}{\rho}$: mass energy-absorption coefficient depends on f .

PRACTICAL IMPLEMENTATION



- X-Rays generator, γ source
- Detection: photo multiplier (NaI, semi-conductors), counter.
- Collimation: thick heavy metal block, drilled, 0,5 mm
- Collimated beam, single spectral line,
- Integrate B-L on a finite length,

$$I = I_0 \exp(-\mu L) = I_0 \exp\left(-\frac{\mu}{\rho} \rho L\right)$$

- At low pressure, little absorption in the gas.

MEASURING THE LINE PHASE FRACTION

- D , diameter, $e/2$ wall thickness.

- Beer-Lambert equation:

$$I = I_0 \exp(-\mu_p e) \exp(-\mu_L(1 - R_{G1})D) \exp(-\mu_G R_{G1}D)$$

- Definition of the gas line fraction:

$$R_{G1}(z, t) \triangleq \frac{L_G}{L_G + L_L} = \frac{L_G}{D}$$

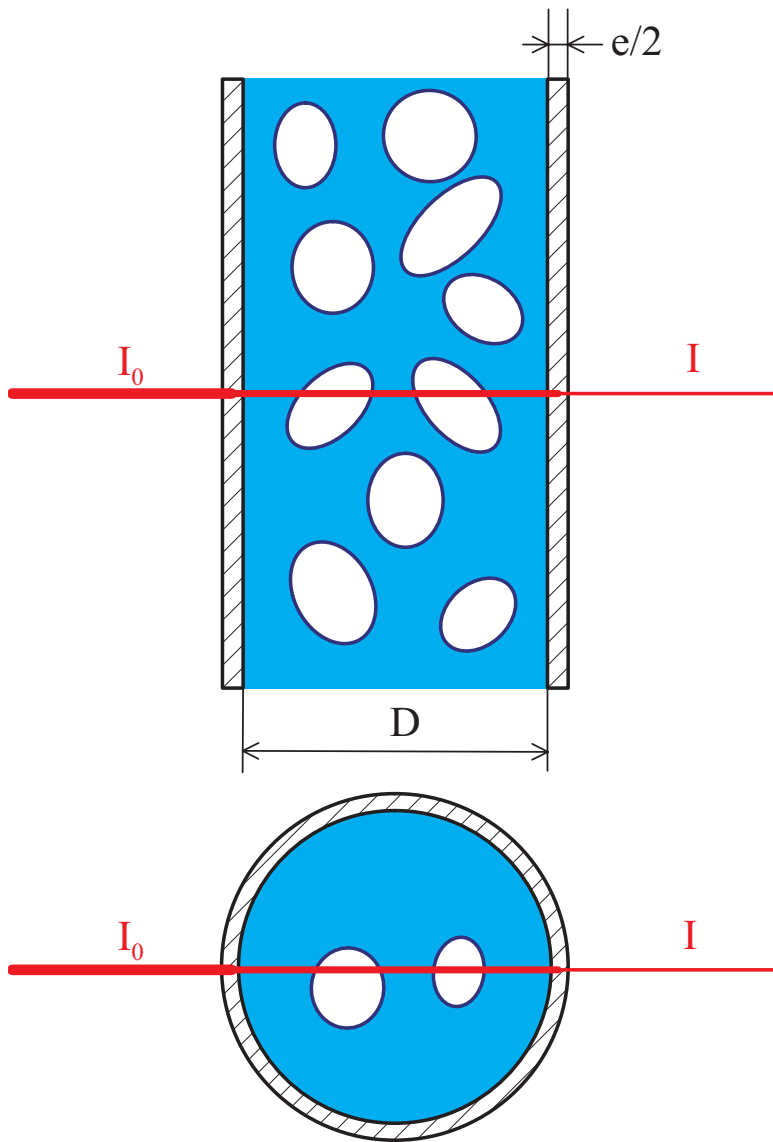
- Low pressure assumption:

$$I_G = I_0 \exp(-\mu_p e)$$

$$I_L = I_0 \exp(-\mu_p e) \exp(-\mu_L D)$$

$$I = I_0 \exp(-\mu_p e) \exp(-\mu_L(1 - R_{G1})D)$$

$$R_{G1} = \frac{\ln I / I_L}{\ln I_G / I_L}$$



Air-water flow, steam-vapor.

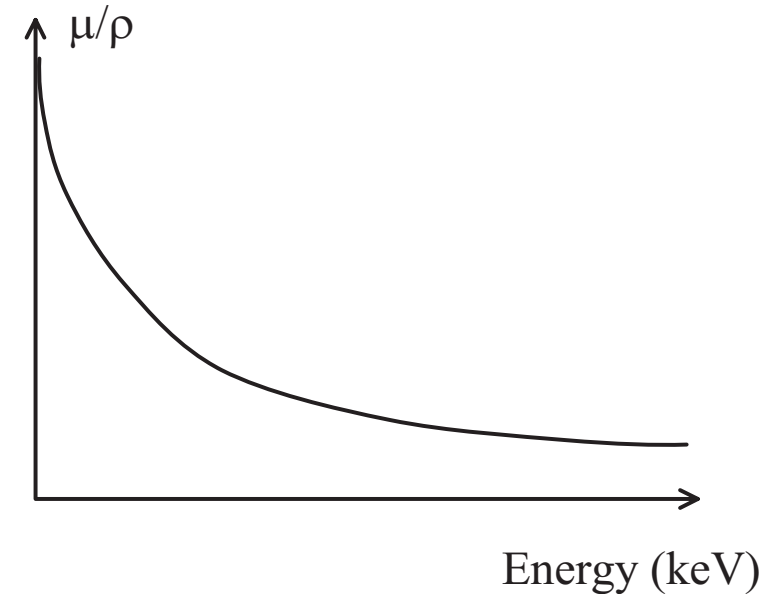
UNCERTAINTY FACTORS

- Contrast $\rightarrow$ low energy

$$\frac{I_G}{I_L} \approx \exp \left(\frac{\mu_L}{\rho_L} \rho_L D \right)$$

- Statistical errors with counters $\rightarrow$ high energy

$$I \propto N, \quad \frac{\Delta N}{N} \propto \sqrt{\frac{1}{N}}$$

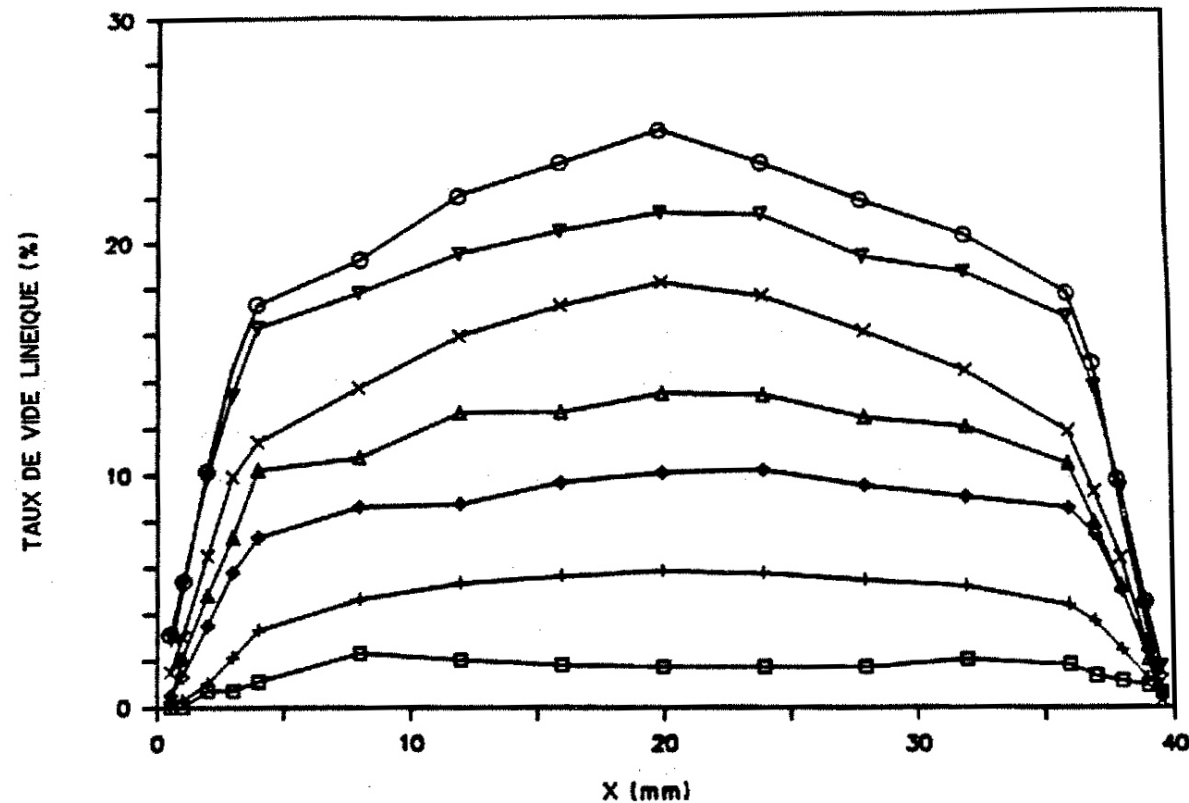


- R_{L1} fluctuations, $I \propto \exp(R_{G1})$ and $\overline{\exp f} \neq \exp \bar{f}$,

$$\Delta R_G \approx 0,20 \text{ (slug)}, \quad \Delta R_G \approx 0,05 \text{ (churn)}.$$

- Source stability: reference beam method, $I \rightarrow \frac{I}{I_0}$.
- Spectral hardening, direct calibration, $I(R_L)$, or use filters.

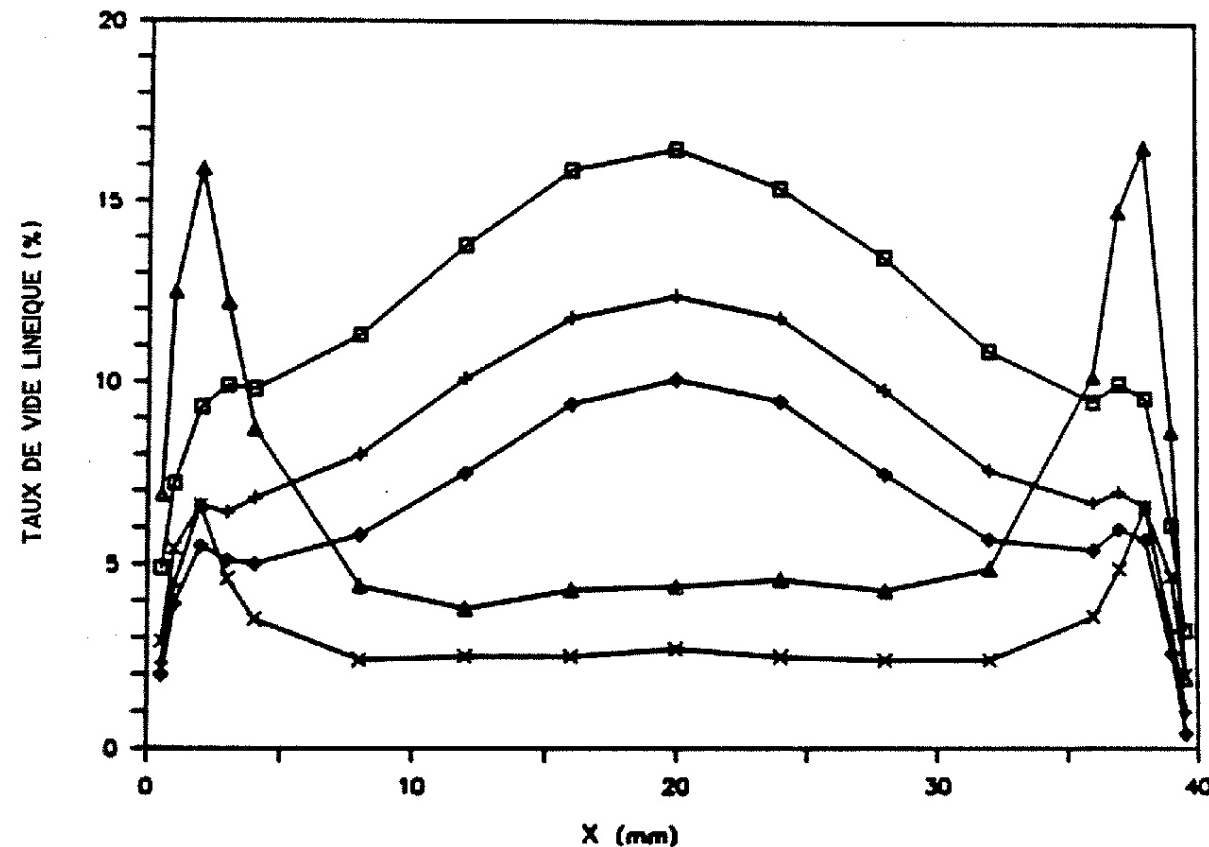
MEAN LINE GAS FRACTION



After Bensler (1990, p. 60)

- No water flow, $J_L = 0$: $\overline{R_{G2}} = 0,01, 0,04, 0,07, 0,10, 0,13, 0,16, 0,19$.

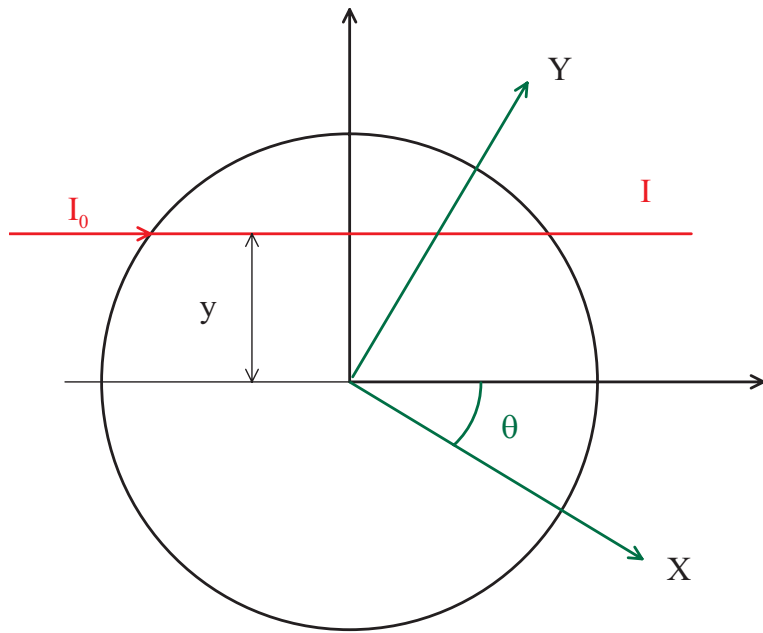
MEAN LINE GAS FRACTION



After [Bensler \(1990, p. 61\)](#)

- Two-phase flow, $J_L = 2$ m/s : $\overline{R_{G2}} = 0,03, 0,061, 0,069, 0,089, 0,123$.
- Wall peaking, still an open problem for modeling...
- Transition in profile shape, bubble clustering, slug flow.

MEAN AREA FRACTION



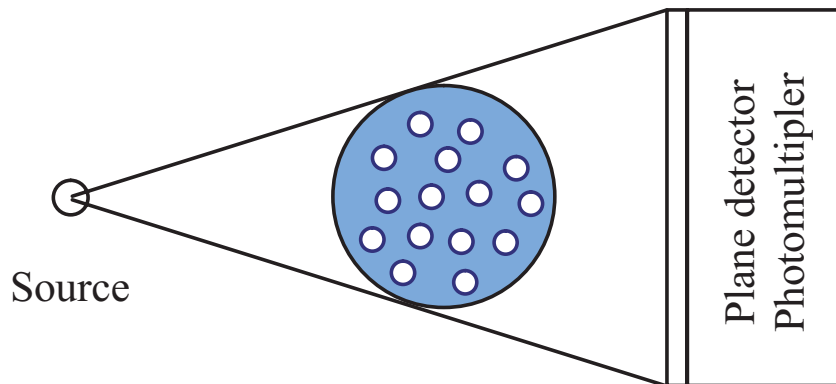
- Mean area fraction, $\overline{R_{G2}}$,

$$\overline{R_{G2}} = \frac{1}{\pi R^2} \int_{-R}^R \overline{R_{G1}}(y) \sqrt{R^2 - y^2} dy$$

- Computed tomography, axis-symmetric,

$$\overline{R_{G1}}(y) \Leftrightarrow \alpha_G(r)$$

$$\overline{R_{G1}}(y, \theta) \Leftrightarrow \alpha_G(X, Y)$$

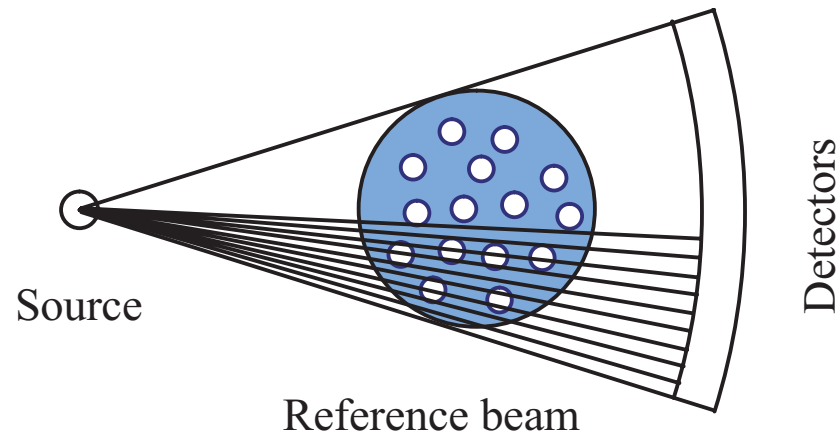


- Instantaneous surface fraction, $R_{G2}(t)$
- Known limitations, Compton, diffusion

$$\Delta R_{G2} \leq 0,05$$

$$0 < R_{G2} < 0,8$$

MEAN AREA FRACTION



- Multibeam densitometer,

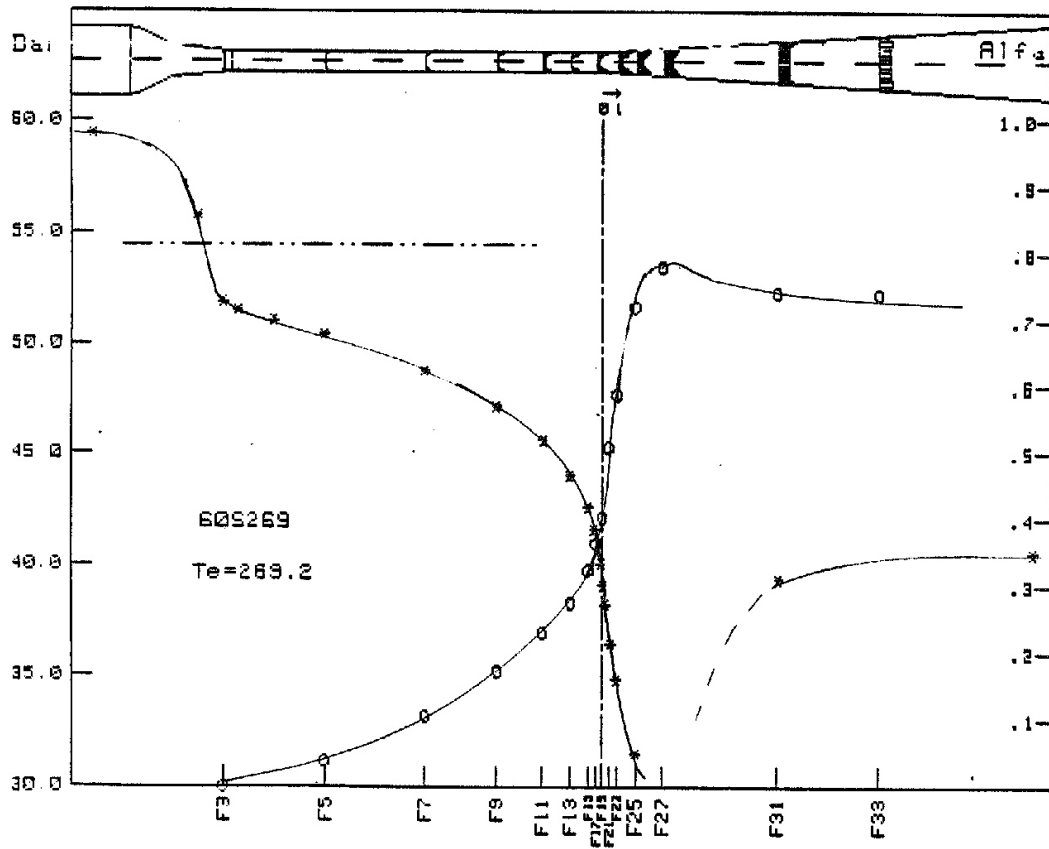
$$R_{G1}(\theta) \Leftrightarrow \alpha_G(r)$$

- XCT, medical scanner

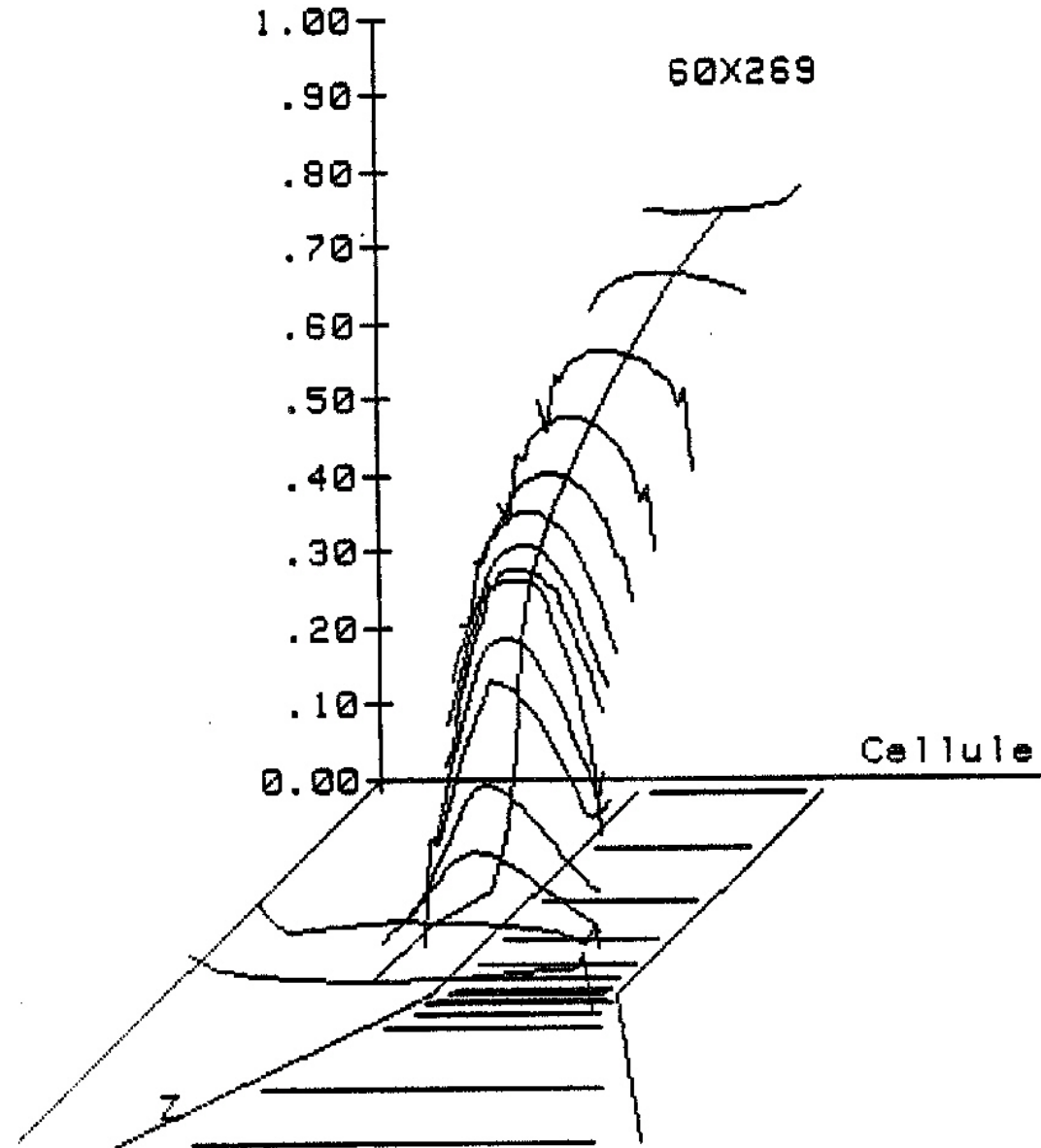
$$\overline{R_{G1}}(\theta, \phi) \Leftrightarrow \alpha_G(x, y)$$

- Neutron diffusion, 90 °
- Low attenuation in steel, diffusion on H nucleus
- Neutron cinematography.

SUPER MOBY DICK



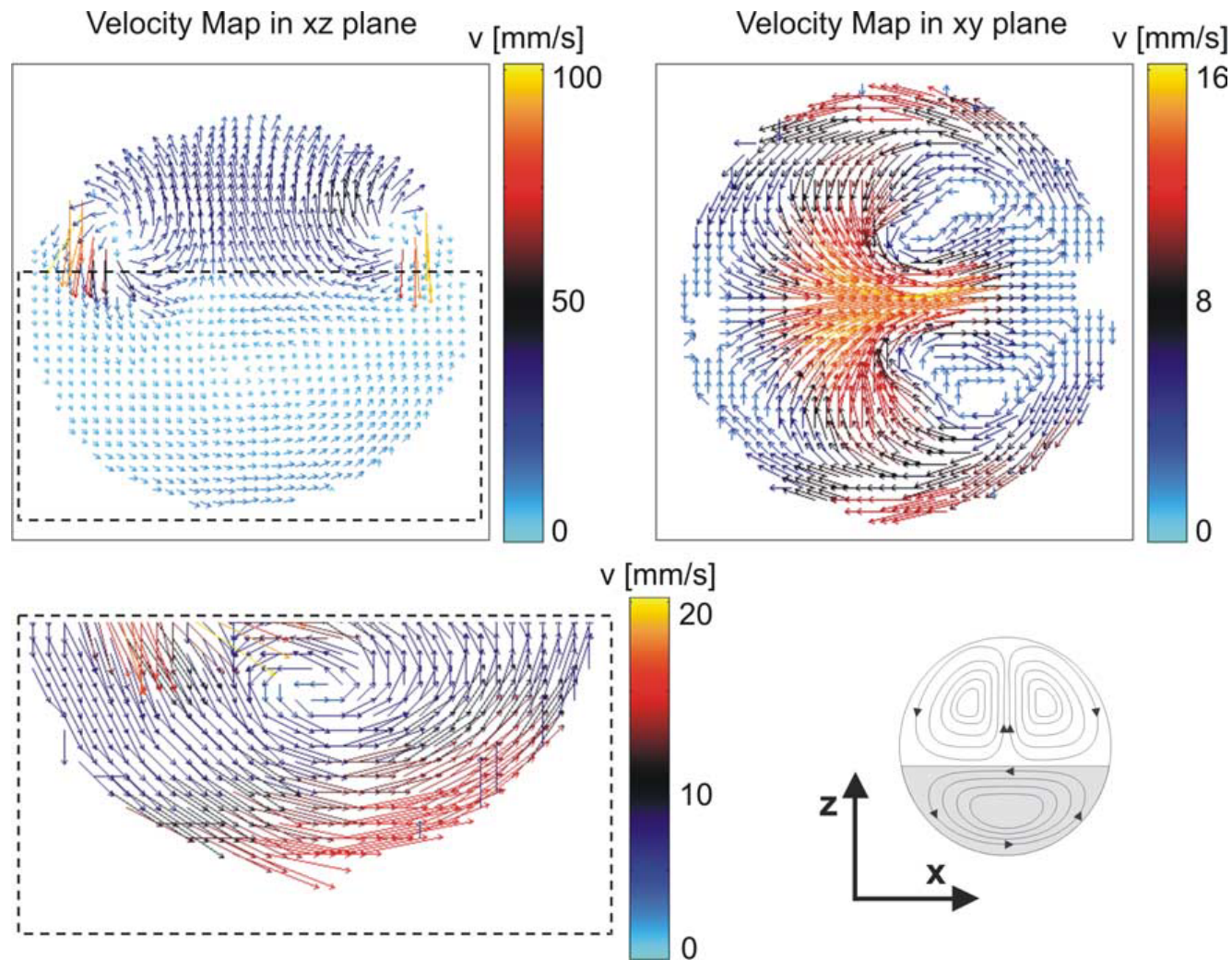
After figures 63'r et 64'r
from [Jeandey et al. \(1981\)](#).
 $P_0 = 59.43$ bar, $T_L = 269.2$ °C,
 $P_{\text{sat}} = 54.31$ bar.



THE ULTIMATE METHOD?

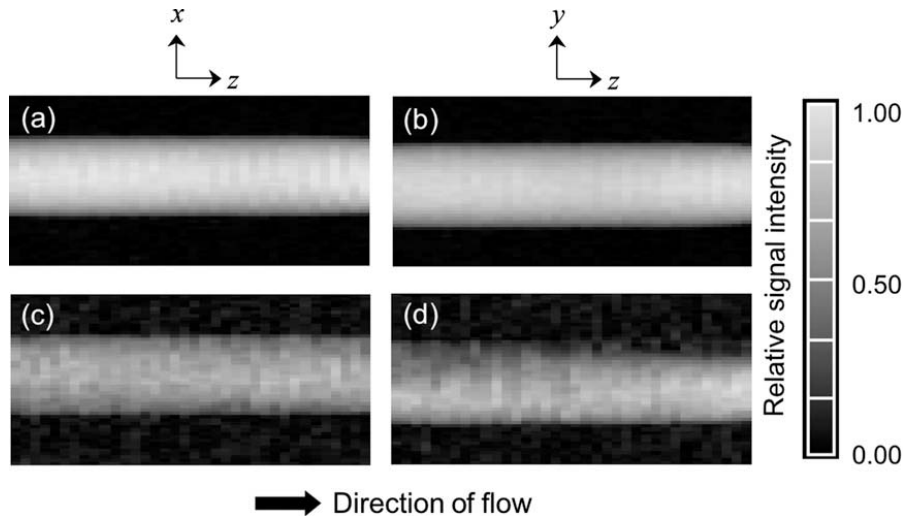
- Nuclear magnetic resonance, NMR, MR imaging
 - Non intrusive method,
 - Magnetization (H, F), magnetic fields
 - Density (void fraction), velocity
- Space and time resolution
 - 0D, 1D, 2D, etc.
 - Time averaged quantities, arbitrary space filters (LES).
 - Turbulent transport phenomena.
- Routine for medicine, body (static) imaging, 1 mm^3 , arterial flow rate, still under development for flow imaging.

FLOW IMAGING OF A LEVITATED DROP

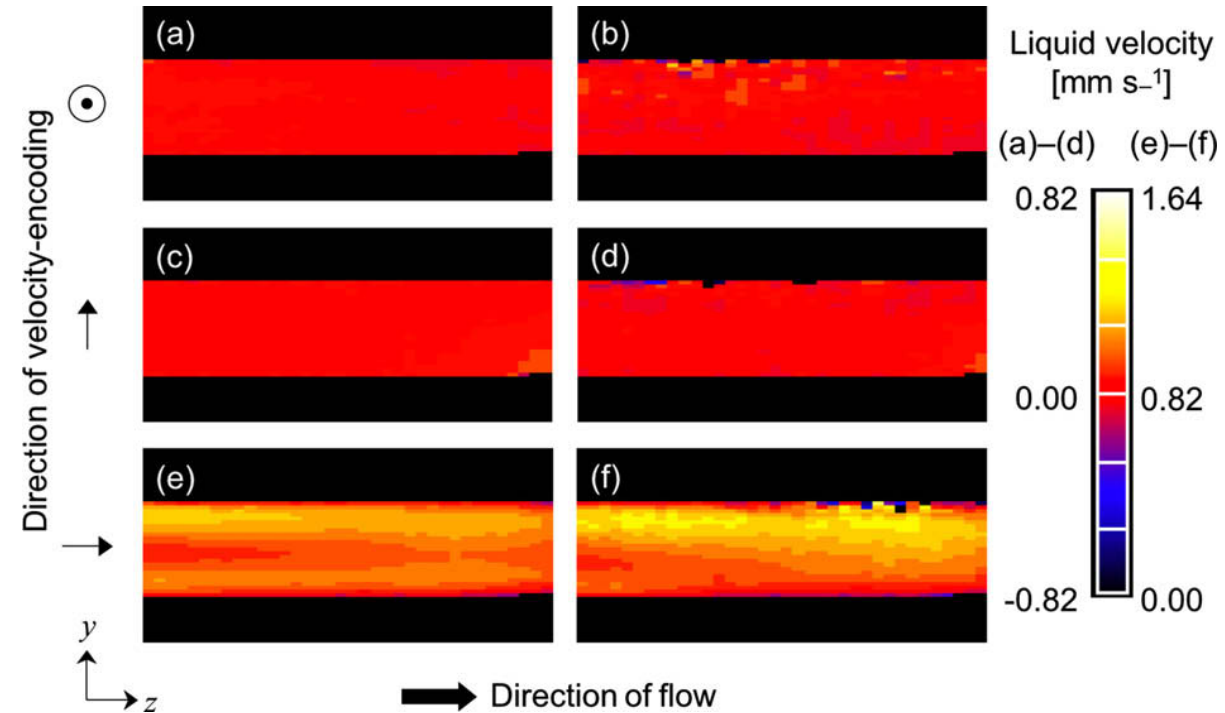


Velocity imaging, after [Amar *et al.* \(2005, Fig. 13\)](#).

VELOCITY & VOID FRACTION IN BUBBLY FLOW



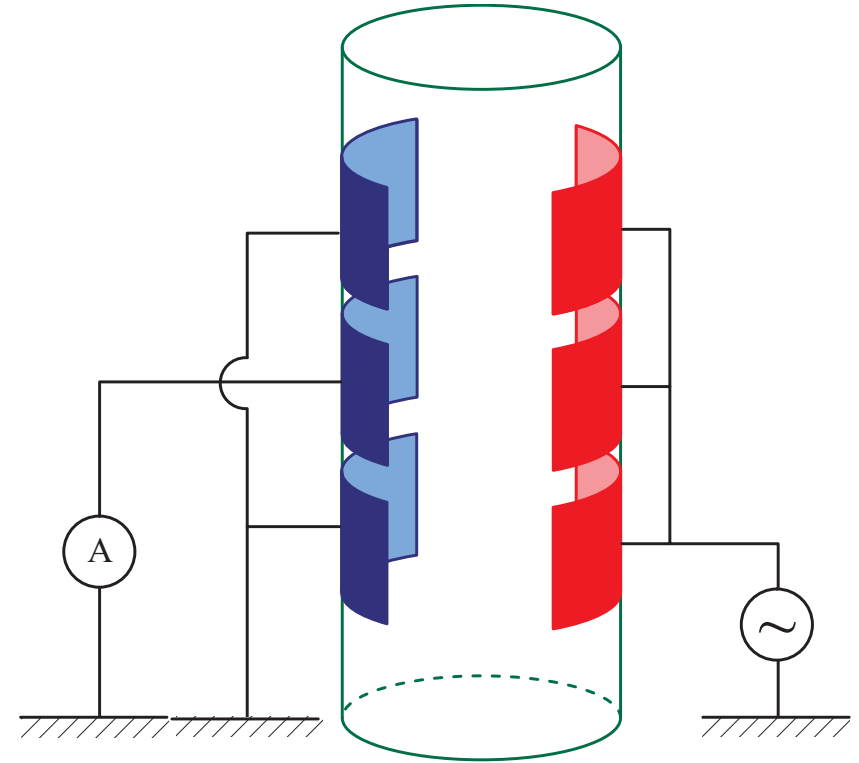
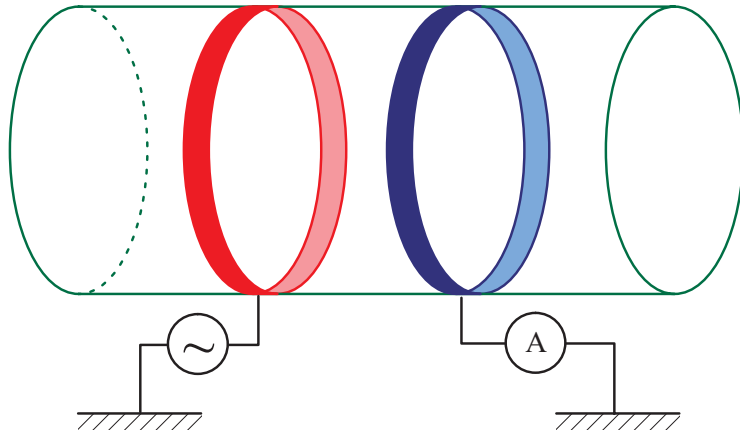
Liquid fraction, $\overline{R_{L1y}}$ and $\overline{R_{L1x}}$



Mean 1D liquid velocity, $\langle \overline{v_{iL}}^{X_L} \rangle_{1x}$.

Horizontal bubbly flow, $D = 13.9$ mm, after [Sankey *et al.* \(2009, Figs 7 and 10\)](#).
Velocity scale is m/s, not mm/s.

IMPEDANCE DENSITOMETRY



- Two-phase medium impedance, excitation voltage, E , signal: current I .

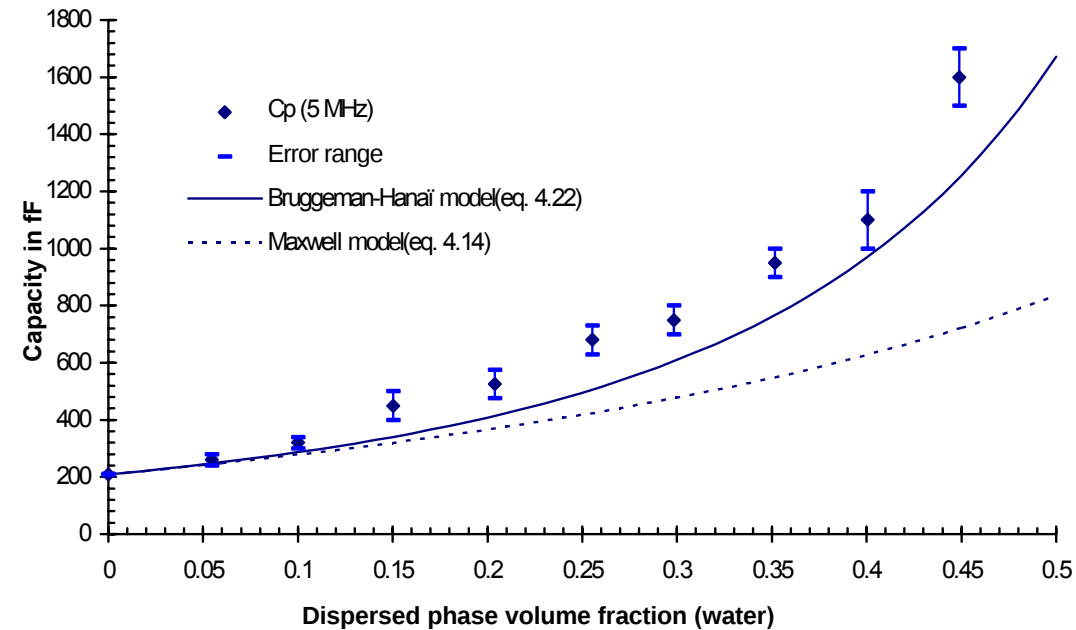
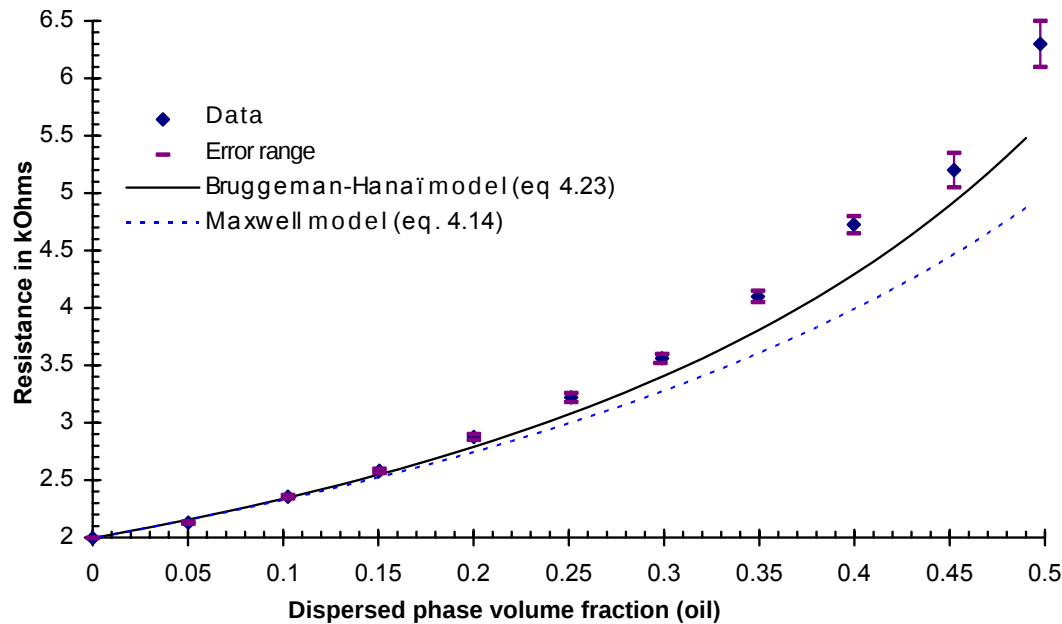
$$I = DE\sigma_C(T, c_1, c_2, \dots)f(R_{G3}, \dots)$$

- Resistive, $\sigma_{2\phi}$, capacitive, $\epsilon_{2\phi}$
- Minimize effect of impedance electrode-medium, $10 < f < 100$ kHz

COMPOSITION-IMPEDANCE RELATION

- Electrode pattern: depends on flow regime.
 - Rings: stratified flow, quasi-linear $I(R_{L2})$, 1D-conductor.
 - Facing electrodes, confine the measuring volume (guard electrodes), bubbly flow, density waves.
- Small integration volume: $R_{G3} \approx R_{G2}(t)$
- Temperature sensitivity: $1^{\circ}\text{C} \approx 1\%$ void fraction.
- Reference method, compensate for effects σ_C variations
$$I \rightarrow \frac{I}{I_0}, I_0 = DE\sigma_C(T, c_1, c_2, \dots)f(0)$$
- Calibration (reference method), numerical modeling (BEM)
- Optimization of electrodes shape (BEM): $f(R_{G2}, \dots) \approx g(R_{G2})$.

OIL-WATER FLOWS

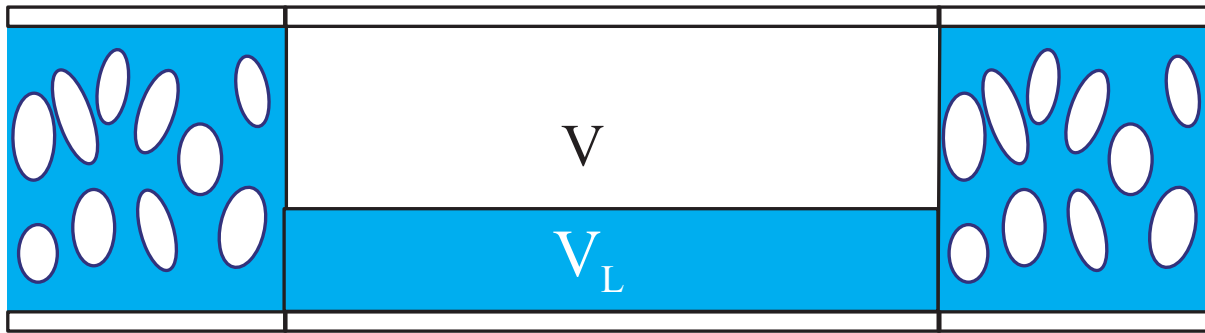


- After Boyer (1992, p. 98)
- Theory for dispersions, Maxwell, Bruggemann, $\sigma_D/\sigma_C \rightarrow 0$,

$$\sigma_{2\phi} \approx \sigma_C (1 - R_{D3})^{3/2}$$

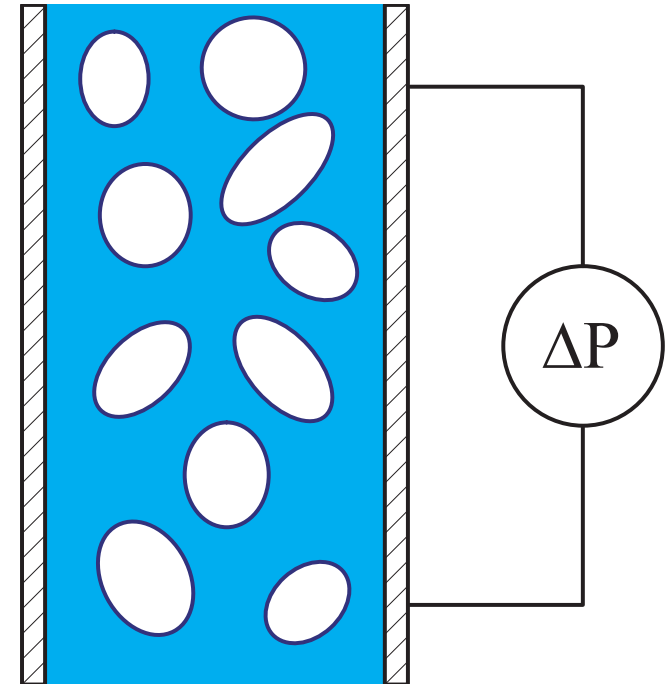
$$\epsilon_{2\phi} \approx \frac{3}{2}\epsilon_D + \left(\epsilon_C - \frac{3}{2}\epsilon_D \right) (1 - R_{D3})^{3/2}$$

VOLUME FRACTION



- Quick closing valves, liquid settling:

$$R_{L3} = \frac{V_L}{V}$$

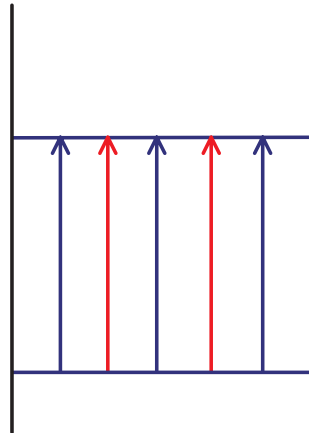


- Gravitational (hydrostatic) pressure drop ($v_L \ll 1$ m/s),

$$\Delta p = \rho g H$$

$$\rho \triangleq \rho_G R_{G3} + \rho_L (1 - R_{G3})$$

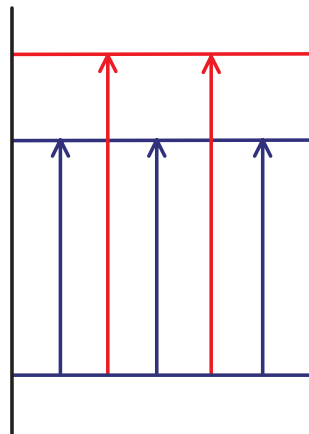
BASIC VOID FRACTION MODELS



1D-1V

Homogeneous

$$\overline{w}_G^X = \overline{w}_L^X = w$$



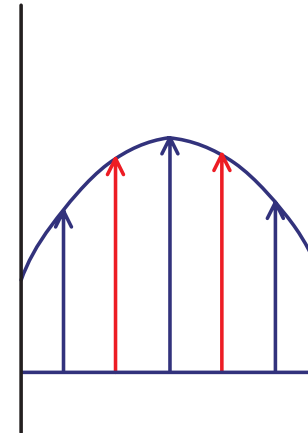
1D-2V

Wallis

$$\overline{w}_G^X = w_G$$

$$\overline{w}_L^X = w_L$$

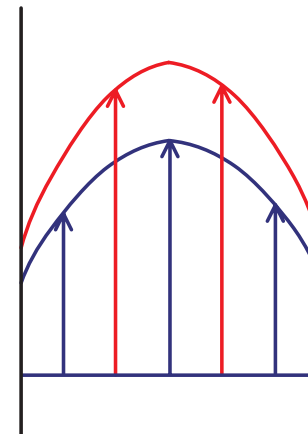
$$w_L \neq w_G$$



2D-1V

Bankoff

$$\overline{w}_G^X = \overline{w}_L^X = f(r)$$



2D-2V

Zuber-Findlay

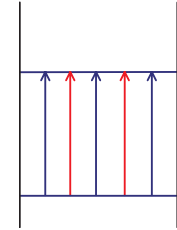
$$\overline{w}_G^X = f(r)$$

$$\overline{w}_L^X = g(r)$$

- Mechanical equilibrium, force balance, bubbly flow (drag-buoyancy), foam (Marangoni-drag-gravity), not inertia controlled.
- Effect of different gas and liquid velocities: $\overline{w}_G^X \neq \overline{w}_L^X$ (on/off)
- Effect of velocity profiles (on/off).

THE HOMOGENEOUS MODEL (1D-1V)

- **1D-1V**, $\overline{w}_G^X = \overline{w}_L^X = w$
 - What is known: $\overline{Q}_G, \overline{Q}_L$.
 - What is unknown: $\overline{R_{G2}} = \langle \alpha_G \rangle_2$.



- Identical derivation for the 4 models. Mean volume flow rate definition,

$$\overline{Q}_G \triangleq \int_{A_G} w_G dA = \overline{A_G \langle w_G \rangle_2} = A \overline{R_{G2} \langle w_G \rangle_2}$$

- Commutativity of averaging operators, uniform velocity profile,

$$\overline{Q}_G = A \overline{R_{G2} \langle w_G \rangle_2} = A \langle \alpha_G \overline{w}_G^X \rangle_2 = A \overline{R_{G2}} w_G$$

- For the liquid and gas phase,

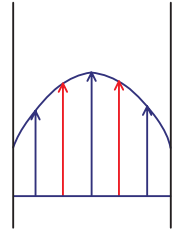
$$\overline{Q}_L = A(1 - \overline{R_{G2}})w_L, \quad \overline{Q}_G = A\overline{R_{G2}}w_G$$

- Identical mean velocities,

$$\frac{\overline{Q}_G}{\overline{Q}_L} = \frac{\overline{R_{G2}}}{1 - \overline{R_{G2}}}, \quad \boxed{\overline{R_{G2}} = \frac{\overline{Q}_G}{\overline{Q}_G + \overline{Q}_L} = \beta}$$

BANKOFF MODEL(2D-1V)

- **2D-1V**, $\overline{w}_G^X = \overline{w}_L^X = w_C \left(\frac{y}{R}\right)^{\frac{1}{m}}$, $\alpha_G = \alpha_C \left(\frac{y}{R}\right)^{\frac{1}{m}}$
- What is known: $\overline{Q}_G$, $\overline{Q}_L$, what is unknown: $\overline{R}_{G2} = \nless \alpha_G \nless_2$.
- Mean volume flow rate definitions,



$$\overline{Q}_G = A \nless \alpha \overline{w}_G^X \nless_2 = Af(w_C, \alpha_C, m, n), \quad \overline{Q}_L = A \nless (1 - \alpha) \overline{w}_L^X \nless_2 = Ag(w_C, \alpha_C, m, n)$$

- Mean velocity and area fraction,

$$\nless \overline{w}_L^X \nless_2 = w_C h(m), \quad \overline{R}_{G2} = \alpha_C k(n)$$

- Eliminate α_C and w_C ,

$$\boxed{\overline{R}_{G2} = K\beta}$$

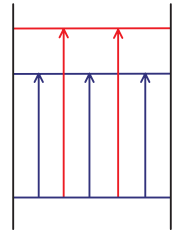
$$K = \frac{2(m+n+mn)(m+n+2mn)}{(n+1)(2n+1)(m+1)(2m+1)}, \quad K = 0,6 \div 1, \quad 2 \leq m, n \leq 7$$

- Closure for steam-water, Bankoff dimensional correlation (p in bar),

$$K = 0,71 + 0,00145p$$

WALLIS MODEL (1D-2V)

- **1D-2V**, $\overline{w}_G^X = w_G$, $\overline{w}_L^X = w_L$, $\alpha_G(r) = \alpha_G$, $w_G \neq w_L$
- What is known: $\overline{Q}_G$, $\overline{Q}_L$, unknown: $\overline{R}_{G2} = \langle \alpha_G \rangle_2$
- Mean flow rates definitions,



$$\overline{Q}_G = A \langle \alpha \overline{w}_G^X \rangle_2 = A \overline{R}_{G2} w_G$$

$$\overline{Q}_L = A \langle (1 - \alpha) \overline{w}_L^X \rangle_2 = A(1 - \overline{R}_{G2}) w_L$$

- Mean surface fraction,

$$\overline{R}_{G2} = \frac{\overline{Q}_G w_L}{\overline{Q}_L w_G + \overline{Q}_G w_L} = \boxed{\frac{\beta}{1 + \frac{(1 - \overline{R}_{G2})(w_G - w_L)}{J}}}$$

- Closure for bubbly flows, w_∞ , terminal velocity ([Clift et al. , 1978](#))

$$w_G - w_L = w_\infty(1 - \overline{R}_{G2}), \quad w_\infty = f(D, \sigma, \rho_L, \rho_G, \mu_L, \dots)$$

- Wallis diagram ([Wallis, 1969](#)), bubble columns, analogy with mass transfer modeling.

SETTING UP THE WALLIS DIAGRAM

- Volumetric flux:

$$\dot{j}_k \triangleq \alpha_k \overline{w}_k^X = \overline{X_k w_k}, \quad \dot{j} = \dot{j}_1 + \dot{j}_2$$

- Drift velocity: phase relative velocity wrt the center of volume,

$$v_{kj} \triangleq \overline{w}_k^X - j$$

- Drift flux, flux of volume in a frame moving with j ,

$$\dot{j}_{GL} = \alpha_G (\overline{w}_G^X - j)$$

- 1D assumption:

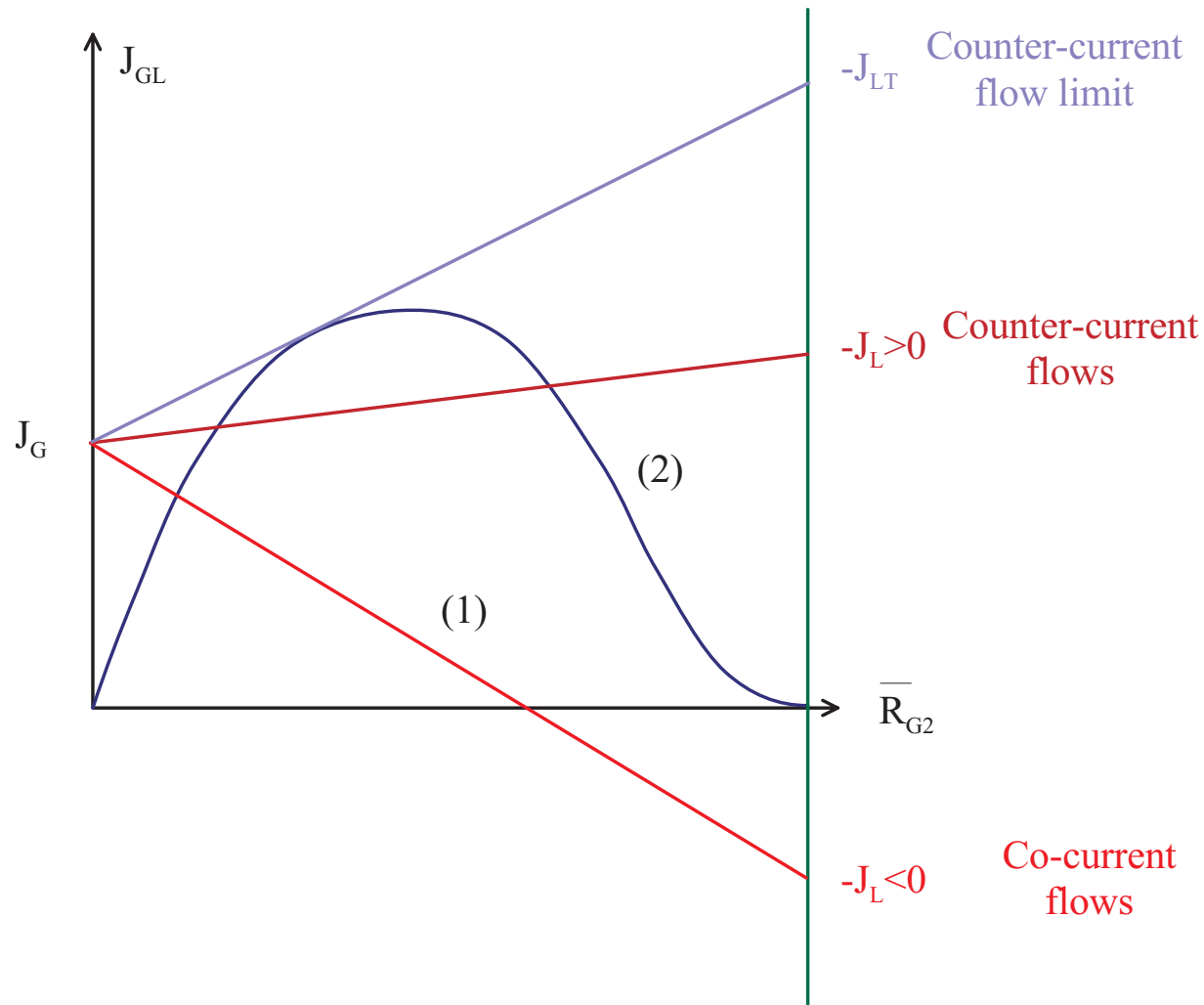
$$\dot{J}_{GL} = \langle \dot{j}_{GL} \rangle_2 = \overline{R_{G2}}(w_G - J) = (1 - \overline{R_{G2}})J_G - \overline{R_{G2}}J_L \quad (1)$$

- By definition: $J = J_G + J_L = \overline{R_{G2}}w_G + (1 - \overline{R_{G2}})w_L$,

$$\dot{J}_{GL} = \overline{R_{G2}}(1 - \overline{R_{G2}})(w_G - w_L) = w_\infty \overline{R_{G2}}(1 - \overline{R_{G2}})^2 \quad (2)$$

- NB: closure is needed (w_∞), e.g bubbly flows, foam.

WALLIS DIAGRAM



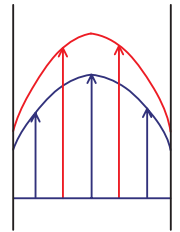
Bubble columns operation.

- Co-current flow: $J_L > 0$, $J_G > 0$, 1 operating condition.
- Counter-current: $J_L < 0$, $J_G > 0$, 2 operating conditions.
- Counter-current flow limitation, $J_L < -J_{LT}$.

ZUBER & FINDLAY MODEL (2D-2V)

- **2V-2D**: what is known: $\overline{Q}_G, \overline{Q}_L$, unknown: $\overline{R_{G2}} = \langle \alpha_G \rangle_2$,
- Definition of the local drift velocity,

$$\overline{w}_{Gj}^X = \overline{w}_G^X - j = (1 - \alpha_G)(\overline{w}_G^X - \overline{w}_L^X)$$



- Mean drift flux on the cross section,

$$\langle \alpha_G \overline{w}_{Gj}^X \rangle_2 = \langle \alpha_G \overline{w}_G^X \rangle_2 - \langle \alpha_G j \rangle_2$$

- Change of variables for unknown quantities:

$$\tilde{w}_{GJ} = \frac{\langle \alpha_G \overline{w}_{Gj}^X \rangle_2}{\langle \alpha_G \rangle_2}, \quad C_0 = \frac{\langle \alpha_G j \rangle_2}{\langle \alpha_G \rangle_2 \langle j \rangle_2}$$

- Previous models are recovered by the Zuber & Findlay model,

$$\boxed{\overline{R_{G2}} = \frac{J_G}{C_0 J + \tilde{w}_{GJ}}} = \frac{\beta}{C_0 + \frac{\tilde{w}_{GJ}}{J}}$$

- Zuber & Findlay diagram: $\frac{J_G}{R_G} = C_0 J + \tilde{w}_{GJ}$

CLOSURES FOR THE ZUBER & FINDLAY MODEL

- ZF diagram, 2 closure relations: C_0 , slope, $\tilde{w}_{GJ}$, y-axis intersection. Flow regime dependent ([Ishii, 1977](#)).
- Here $\overline{R_{G2}} \rightarrow R_G$ is to be understood,

$$C_0 = \left(1, 2 - 0, 2\sqrt{\frac{\rho_G}{\rho_L}}\right) \underbrace{(1 - \exp(-18R_G))}_{\text{boiling only}}$$

- Bubbly flows:

$$\tilde{w}_{GJ} = (C_0 - 1)J + 1,4 \left(\frac{\sigma g(\rho_L - \rho_G)}{\rho_L^2} \right)^{1/4} (1 - R_G)^{7/4}$$

- Slug flow:

$$\tilde{w}_{GJ} = (C_0 - 1)J + 0,35 \left(\frac{gD(\rho_L - \rho_G)}{\rho_L} \right)^{1/2}$$

ZUBER & FINDLAY MODEL CLOSURES (CT'D)

- Churn flow:

$$\tilde{w}_{GJ} = (C_0 - 1)J + 1,4 \left(\frac{\sigma g(\rho_L - \rho_G)}{\rho_L^2} \right)^{1/4}$$

- Annular flow:

$$\tilde{w}_{GJ} = \frac{1 - R_G}{R_G + \left(\frac{1+75(1-R_G)}{\sqrt{R_G}} \frac{\rho_G}{\rho_L} \right)^{1/2}} \left(\sqrt{\frac{gD(\rho_L - \rho_G)(1 - R_G)}{0,015\rho_L}} \right)$$

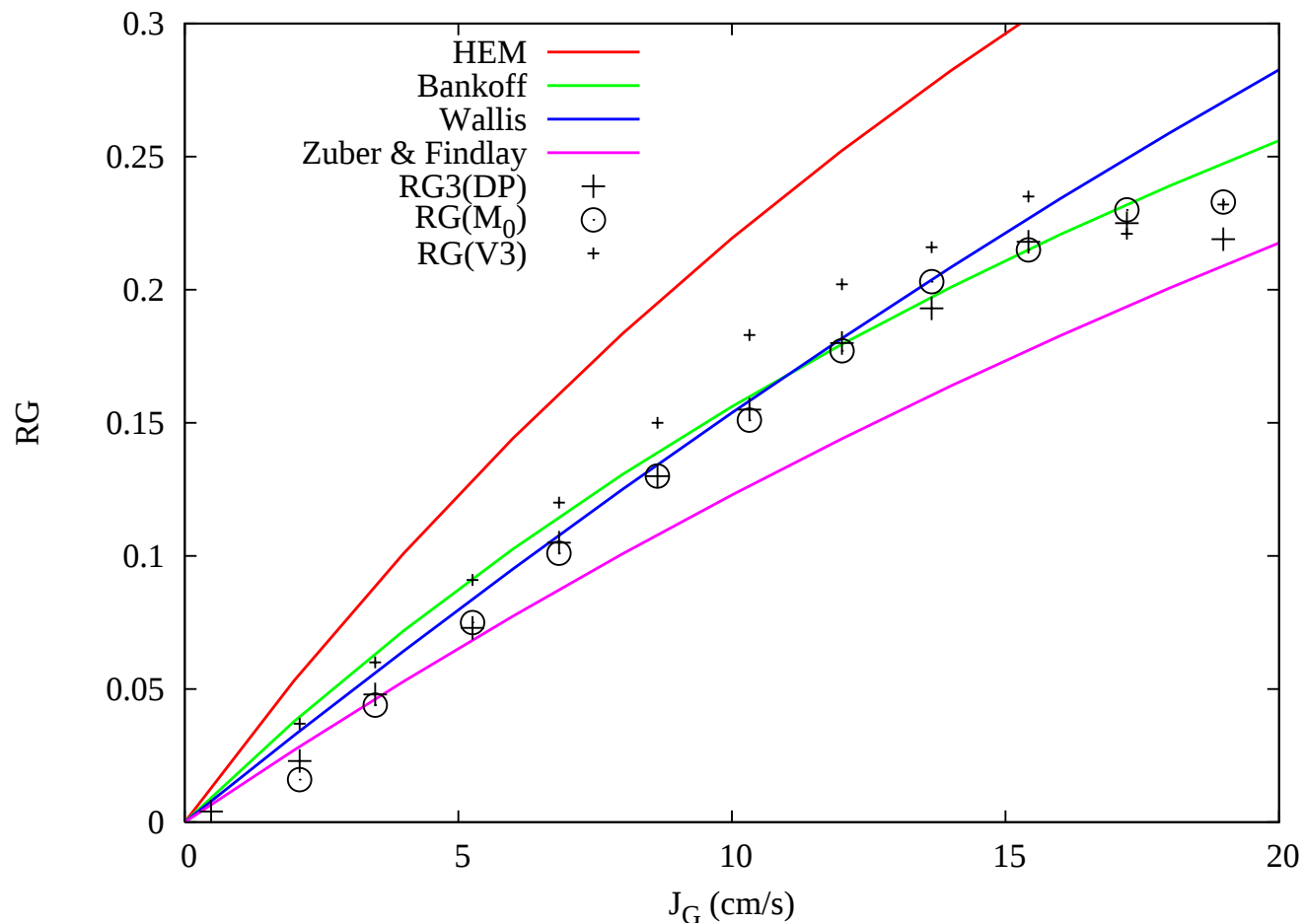
REFERENCE GUIDE, WANT TO KNOW MORE

- Modeling the void fraction: [Delhaye \(2008\)](#).
- Drift flux modeling: [Wallis \(1969\)](#).
- Closures: [Ishii \(1977\)](#), see also the enhanced and revised edition by [Ishii & Hibiki \(2006\)](#).

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SUGGESTED HOMEWORK ON VOID FRACTION



Objective of the homework: utilize the void fraction models to analyze NMR low liquid velocity data (35 cm/s). Build the Wallis and the Zuber & Findlay diagrams.